

Lecture 2. Dimensional analysis (II)

{ Casimir force

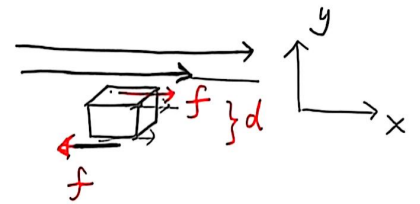
{ Bending a plastic rod $F = \gamma \frac{r^4}{l^2} \cdot \alpha$

{ Fluid mechanics - Reynold number $R = \frac{\rho v d}{\eta} \Rightarrow [\eta] = \text{angular momentum density}$

flux - poiseuille formula $Q = \frac{\Delta P}{\Delta l} \frac{d^4}{2} f(R)$

drag coefficient $f = \rho v^2 d^2 C(R)$

wind tunnel design



unit of η

$$\frac{f}{A} = \eta \frac{\partial u_x}{\partial y}$$

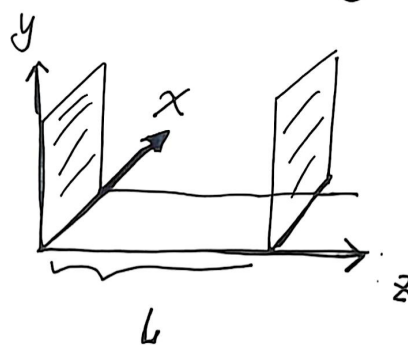
$\tau^{-1} = \frac{\partial u_x}{\partial y}$
time constant

$$\Rightarrow \frac{f \tau \cdot d}{A \cdot d} = \eta \Rightarrow \boxed{\frac{\Delta L}{Vol} = \eta}$$

Hence $\boxed{\frac{\eta}{\rho v d} = R}$

§1. Casimir force.

Two infinitely large metallic plates put in parallel with distance L in the vacuum.



What's the force per area on the plates?

We can set up the Helmholtz Eq for the E&M field with the boundary

Condition.

$$\vec{E} e^{-i\omega t}$$

$$\begin{cases} \nabla^2 \vec{E} + k^2 \vec{E} = 0 \\ \nabla \cdot \vec{E} = 0 \\ \vec{E}_t |_{\text{boundary}} = 0 \end{cases}$$

\vec{E}_t is the tangential component to the boundary.

$$E_{x,y}(x,y,0) = E_{x,y}(x,y,z=L) = 0 \Rightarrow E_{x,y} = E_{0,x,y} e^{i(k_x x + k_y y)} \sin k_z z \quad (*)$$

with $k_z = \frac{n\pi}{L}$, ($n=1,2,\dots$).

$$E_z = E_{0,z} e^{i(k_x x + k_y y)} \cos k_z z, \quad \text{such that}$$

$$\nabla \cdot \vec{E} = (E_{0,x} i k_x + E_{0,y} i k_y - k_z E_{0,z}) e^{i(k_x x + k_y y)} \sin k_z z = 0$$

$$\Rightarrow k_z E_{0,z} = i(k_x E_{0,x} + k_y E_{0,y})$$

Dispersion $\Rightarrow k^2 = k_x^2 + k_y^2 + \frac{n^2 \pi^2}{L^2} \leftarrow \omega = |k| c = \sqrt{k_x^2 + k_y^2 + \left(\frac{n\pi}{L}\right)^2} \cdot c$

Consider, $k_x = k_y = 0$, $n=1$, $\Rightarrow E_x = E_{0,x} \sin \frac{\pi}{L} z$

a configuration $E_{0,y} = E_{0,z} = 0$.

$$B_y = B_{0,y} \cos \frac{\pi}{L} z$$

$$\nabla \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}$$

with $\frac{B_{0,y}}{E_{0,x}} = \frac{c}{i\omega} k_z = -i$.

$$\frac{\partial}{\partial z} E_x - \frac{\partial}{\partial x} E_z = -\frac{1}{c} B_y (-i\omega)$$

Even in the vacuum, there exist zero point energy of the E & M modes. Nevertheless, the naive calculation results in infinity. Renormalization is needed to extract meaningful finite results. Using dimensional analysis, we arrive at:

$P = F/A$, depends on L, \hbar, c . Only one dimensionless quantity can be constructed among P, L, \hbar, c .

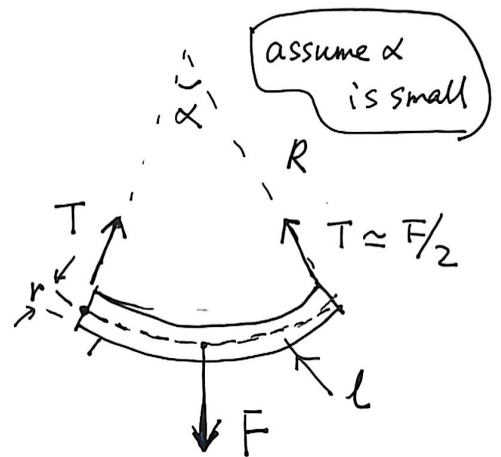
$$P = \frac{[E]}{[L^3]} = \frac{\hbar/[T]}{[L^3]} = \frac{\hbar c/[L]}{[L^3]} \sim \frac{\hbar c}{L^4}$$

However, dimensional analysis can not determine P is repulsive or attractive. (Nevertheless, recently there appears new understanding. The current and charge fluctuations between two plates coordinate together to achieve an attraction.)

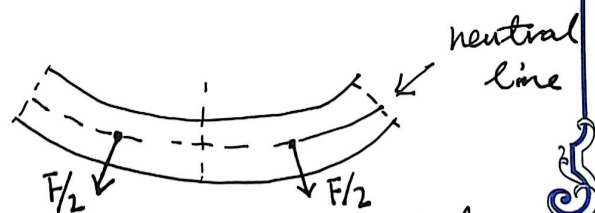
§2. Bending of plastic rod.

A rod of length l . It's bent under the push of the force F at the center and the forces T at the ends. The bending angle is α . The radius of the rod is r .

The rod's Young's modulus is γ .

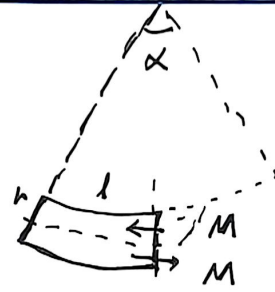


There exists a neutral line which is kept at the original length l .



Above the neutral line, it's compressed; Below it's stretched.

Consider the distortion
of the left-hand side.



$$\left. \begin{aligned} R \cdot \alpha &= l \\ (R \pm r) \alpha &= l \pm \Delta l \end{aligned} \right\} \Rightarrow r \cdot \alpha = \Delta l$$

If we fix α , the strain $\frac{\Delta l}{l} = \frac{r}{R} \cdot \alpha$.

On the other hand, the bending effect \propto the torque $\sim F \cdot l$

Hence, if fix other parameters, $F \propto l^{-2}$.

Then dimensional analysis yield

$$[F] = [P][A] = [Y][L^2] = [Y][r^4][l^{-2}]$$

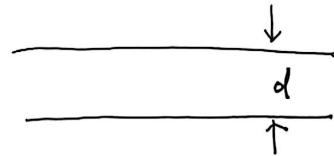
$$P = Y \frac{\Delta l}{l}$$

F should proportional to the bending angle $\Rightarrow F \propto Y \frac{r^4}{l^2} \cdot \alpha$

If we apply it to a bow, it means a thicker bow is much more difficult to pull the bow.

§ Fluid mechanics example

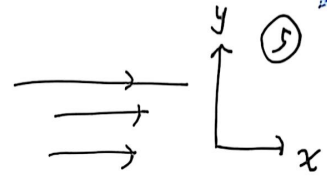
Consider a pipe with the diameter d .



Fluid with density ρ , viscosity η , flow velocity v ,

pressure gradient $\Delta P / \Delta l$. We can construct $5 - 3 = 2$ two

dimensionless quantities.



check η 's dimension: $\frac{f}{A} = \eta \cdot \frac{\partial v_x}{\partial y}$

$$[\eta] = [F][L] / [L^2] \cdot [v] = [F][T] / [L^2] = \frac{[\text{angular momentum}]}{[L^3]}$$

$$= [M][L]^{-1}[T]^{-1}$$

$$\Delta P / \Delta l = [F] / [L^2] = [M][L]^{-2}[T]^{-2}$$

	M	L	T
ρ	1	-3	0
d	0	1	0
v	0	1	-1
η	1	-1	-1
$\Delta P / \Delta l$	1	-2	-2

$$\Rightarrow \left. \begin{aligned} [\rho/\eta] &= [L]^{-2}[T] \\ [dv] &= [L][T]^{-1} \end{aligned} \right\} \Rightarrow \frac{\rho d v}{\eta} = \Pi_1$$

(Reynolds number)

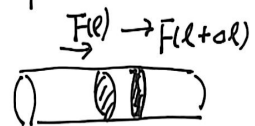
what's the physical meaning of Π_1 : Consider a ball of diameter d . It falls in the air. The resistance has two contributions of linear drag and quadratic drag. The quadratic drag is due to pushing the air to move with ball. $F_2 = \rho v^2 \cdot d^2$. The linear drag is due to

viscosity $F_1 \approx \eta d v \Rightarrow \boxed{\frac{F_2}{F_1} = \frac{\rho d v}{\eta} = \Pi_1 = R}$

$\Delta P / \Delta l$ is the force density, $[\Delta P / \Delta l \cdot d] \sim$ energy density

hence $\boxed{\frac{(\Delta P / \Delta l) d}{\rho v^2} = \Pi_2}$

The Reynolds number has important meaning. For example, $\frac{\partial F}{\partial l}$ the pressure gradient ~~at~~ at a cross section



$$\frac{\Delta F}{\Delta l} = \frac{\Delta P}{l} \cdot S$$

From Π_2 , we can express $\frac{\Delta P}{\Delta L} \sim \frac{\rho v^2}{d} \cdot \Phi(R)$ ← R is another dimensionless quantity

$$\Rightarrow \frac{\Delta F}{\Delta L} \sim \frac{\rho v^2}{d} \cdot \overbrace{\frac{\pi}{4} d^2}^S \Phi(R) \sim \rho v^2 d \Phi(R)$$

flux

$$\Rightarrow Q = \bar{v} S = \frac{d}{\rho v \Phi(R)} \frac{\Delta F}{\Delta L} \sim \frac{d^3}{\rho v \Phi(R)} \frac{\Delta P}{\Delta L} = \frac{d^4}{R \Phi(R) \eta} \frac{\Delta P}{\Delta L}$$

$$\Rightarrow Q = \frac{\Delta P}{\Delta L} \frac{d^4}{\eta} P(R)$$

only rely on $R = \frac{\rho d v}{\eta}$

$$P(R) \propto \frac{1}{R \Phi(R)}$$

In principle, we could use water as an example to measure $\Phi(R)$ or, $P(R)$, and apply it to other liquids, even air (when we neglect its compressibility at $v \ll v_{\text{sound}}$).

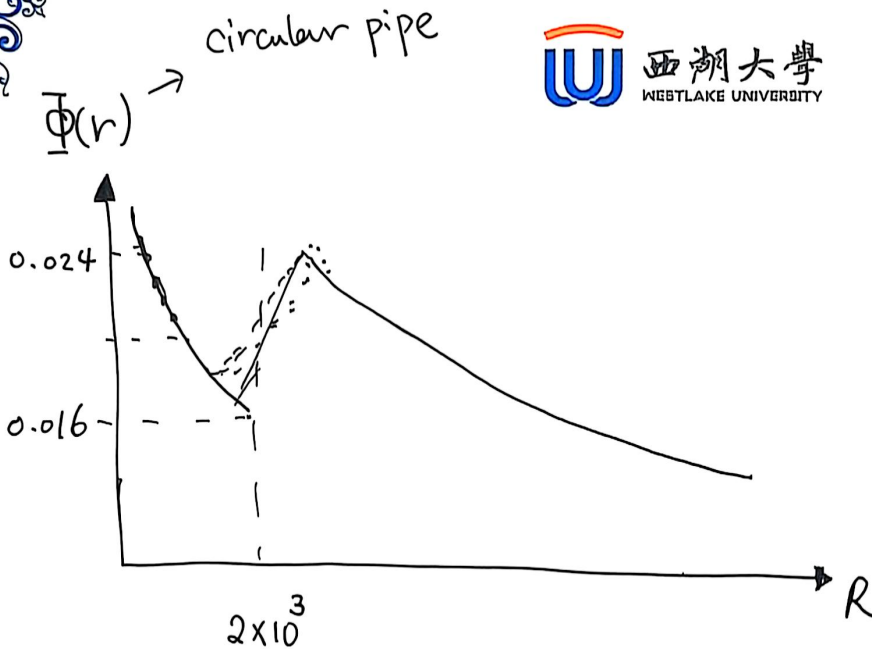
⊗ laminar flow v. s. turbulence

We expect two different behaviors of $\Phi(R)$, or $P(R)$. For laminar flow, there's no acceleration. The flow velocity is only determined by the friction, not by its density ρ . Hence, $P(R)$ should be a constant, i.e.

$$Q = \frac{\Delta P}{\Delta L} \frac{d^4}{\eta} \cdot C \leftarrow C = \frac{\pi}{128} \text{ from theory calculation.}$$

$$\text{(Poiseuille formula)} \Rightarrow \Phi(R) \propto R^{-1}$$

But for turbulence $\Phi(R)$ behaves very differently.



(*) Drag force revisit

physical quantities: $\rho, v, d, f, \eta \rightarrow 2$ dimensionless quantities.

$$[f] = [\text{Pressure}][A] = \frac{[\text{energy}]}{[V]} [A]$$

$$= \frac{[M][V]^2}{[V]} [A] = [\rho][v]^2 [d]^2$$

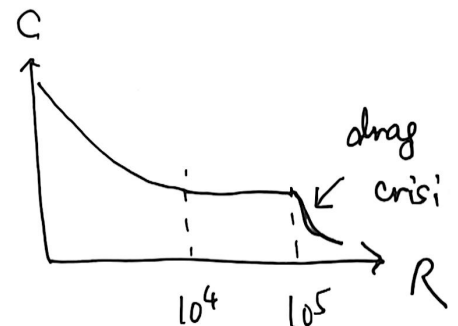
Additionally $C_D(R)$ with $R = \rho v d / \eta$

$$\Rightarrow f = \rho v^2 d^2 C_D(R), \quad C_D(R) = \frac{C_1}{R} + C_2 + \dots$$

At R small, drag coefficient $\propto R^{-1}$,

as $R \sim 10^3 \sim 10^5$ $C_D(R)$ is independent on R .

Wind tunnel: $R = \rho v d / \eta$



If we use model d is smaller than the real object,

nevertheless, we can use larger v , or larger ρ to maintain the same Reynolds number.