

Lecture 11 Conservation laws (I)

§1. General statements: symmetry \rightarrow conservation laws

Sym — same, metry — measure.

translation symmetry \rightarrow momentum conservation

$$L(\dot{x}, t) \quad P = \frac{\partial L}{\partial \dot{x}} \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) = + \frac{\partial L}{\partial x} = 0 \Rightarrow \frac{d}{dt} P = 0.$$

homogeneity of space

rotational symmetry \rightarrow angular momentum conservation

$$L(\dot{\phi}, t) \quad L = \frac{\partial L}{\partial \dot{\phi}} \quad \frac{d}{dt} (L) = \frac{\partial L}{\partial \phi} = 0 \Rightarrow L = 0.$$

why? If the space is homogeneous, one point is no more special than the other.

If a particle is at rest at some place, it has no motivation to move to other place. If it's moving, it spends equal time in traveling the same length interval ^{at} any point along its trajectory.

charge conservation is more subtle, which a result of some internal symmetry. Conservation law leads to continuity equation. Charge cannot be destroyed and cannot be created. Whenever charge changes locally, it means that there's a current flow to transfer charge to other place.

$$Q(t) = \int p(r, t) dr, \quad \frac{dQ}{dt} = - \oint \vec{j} \cdot d\vec{a} = - \iiint \nabla \cdot \vec{j} dv \Rightarrow \frac{\partial p}{\partial t} + \nabla \cdot \vec{j} = 0$$

(2)

Continuity equation should be valid in any frame. \Rightarrow it must be relativistic invariant! $(CP, \rho\vec{v})$, $(\frac{1}{c}\frac{\partial}{\partial t}, -\frac{\partial}{\partial x})$ are relativistic vectors which satisfy Lorentz transformation. \Rightarrow inner product is invariant

$$\boxed{\frac{\partial}{\partial t} \rho + \nabla \cdot \vec{j} = 0}$$

§ Poynting's theorem

$$U = \int d^3x \left(\frac{E^2}{8\pi} + \frac{B^2}{8\pi} \right). \quad \text{Is this energy conserved?}$$

We have to take into the dissipation - the work done by E-M force.

$$\vec{F} \cdot d\vec{l} = q(\vec{E} + \frac{\vec{v}}{c} \times \vec{B}) \cdot \vec{v} dt = q \vec{E} \cdot \vec{v} dt \quad \nabla \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$\underset{\text{power}}{\frac{dw}{dt}} = \int_V \vec{E} \cdot \vec{j} d^3r = \int_V d^3r \vec{E} \cdot \left[\frac{c \nabla \times \vec{B}}{4\pi} - \frac{1}{4\pi} \frac{\partial \vec{E}}{\partial t} \right]$$

$$\nabla \cdot (\vec{E} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{E}) - \vec{E} \cdot (\nabla \times \vec{B})$$

$$\Rightarrow \frac{dw}{dt} = \int d^3r C \left[\frac{\vec{B} \cdot (\nabla \times \vec{E}) - \nabla \cdot (\vec{E} \times \vec{B})}{4\pi} \right] - \frac{1}{4\pi} \vec{E} \cdot \frac{\partial \vec{E}}{\partial t}$$

$$= \int d^3r \frac{-1}{8\pi} \frac{\partial}{\partial t} (E^2 + B^2) - \oint \frac{C}{4\pi} (\vec{E} \times \vec{B}) \cdot d\vec{a}$$

$$\Rightarrow \text{or } \int d^3r \frac{\partial}{\partial t} U_{em} + \oint \frac{C}{4\pi} (\vec{E} \times \vec{B}) \cdot d\vec{a} = - \frac{dw}{dt} \quad \begin{matrix} \leftarrow \text{The energy cost} \\ \text{from EM to other} \\ \text{energy.} \end{matrix}$$

$$\frac{\partial}{\partial t} U_{em} + \frac{c}{4\pi} \nabla \cdot (\vec{E} \times \vec{B}) = - \vec{E} \cdot \vec{j} \xrightarrow[E.M]{\text{energy leaking}}$$

$$\Rightarrow \text{EM energy flow } \vec{S} = \frac{c}{4\pi} \vec{E} \times \vec{B}. \quad \vec{E} \cdot \vec{j} = \frac{\partial}{\partial t} U_{mech}$$

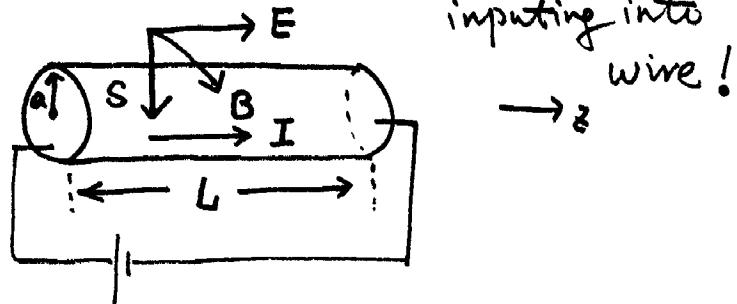
$$\boxed{\frac{\partial}{\partial t} (U_{em} + U_{mech}) + \nabla \cdot \vec{S} = 0}$$

Example: where's the energy comes from? from the field inputting into wire!

$$E = \frac{V}{L}$$

$$\text{Power} = VI$$

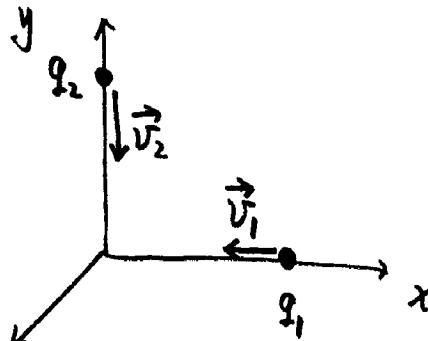
$$B = \frac{2}{rc} I$$



$$\text{at the surface } \vec{S} = \frac{c}{4\pi} \vec{E} \times \vec{B} = \frac{1}{a} \frac{V}{2\pi L} \cdot I \quad \hat{e}_z \times \hat{e}_\phi = \frac{VI}{aL^2\pi} \hat{e}_\rho$$

$$\Rightarrow \oint d\vec{a} \cdot \vec{S} = 2\pi a \cdot L \frac{VI}{aL^2\pi} = VI.$$

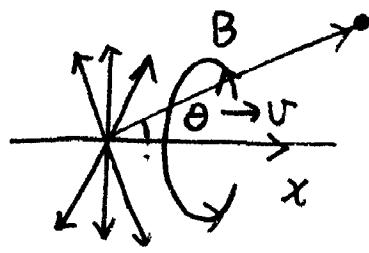
§ momentum conservation:



Consider two charges q_1 and q_2 moving along $-\hat{x}$ and $-\hat{y}$ axis, do their interacting forces obey Newton's 3rd law?

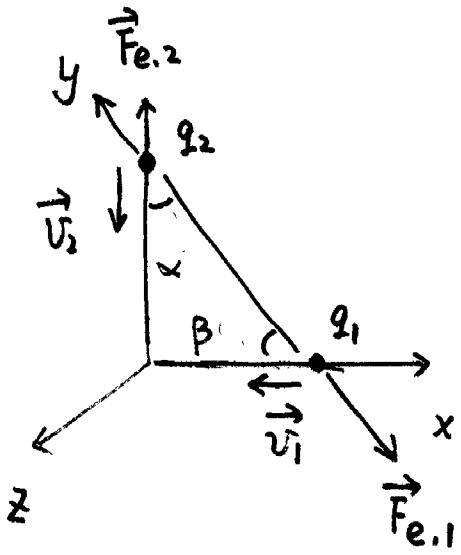
(4)

As we learned this quarter, a moving charge generates an E-field



which is still radial, but more concentrated around the equatorial plane. It also has the magnetic field following the right hand law

$$\vec{B} = \frac{\vec{v} \times \vec{E}}{c}, \quad \vec{E} = \frac{Q \hat{r}}{r^3} \frac{1 - \beta^2}{(1 - \beta^2 \sin^2 \theta)^{3/2}}.$$

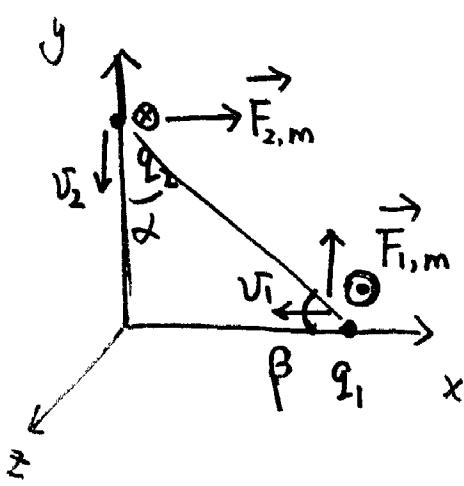


$\vec{F}_{e,1}$ and $\vec{F}_{e,2}$ are opposite directions. But their magnitudes are not the same

$$F_{e,1} = \frac{q_2 q_1}{r_1^2} \frac{1 - \beta_2^2}{(1 - \beta_2^2 \sin^2 \alpha)^{3/2}}, \quad \beta_2 = \frac{v_2}{c}.$$

$$F_{e,2} = \frac{q_2 q_1}{r_2^2} \frac{1 - \beta_1^2}{(1 - \beta_1^2 \sin^2 \beta)^{3/2}}, \quad \beta_1 = \frac{v_1}{c}.$$

The magnetic forces are not even co-linear.



$$\vec{F}_{1,m} = \frac{v_1}{c} \frac{v_2}{c} \frac{q_1 q_2}{r^2} \frac{1 - \beta_2^2}{(1 - \beta_2^2 \sin^2 \alpha)^{3/2}} \hat{y}$$

$$\vec{F}_{2,m} = \frac{v_2}{c} \frac{v_1}{c} \frac{q_1 q_2}{r^2} \frac{1 - \beta_1^2}{(1 - \beta_1^2 \sin^2 \beta)^{3/2}} \hat{x}$$

but how to maintain momentum

conservation? Field contains momentum. We cannot just consider particles, but consider they are embedded in E-M field

§ Maxwell stress tensor.

The E-M force density $\vec{F} = \int \vec{f} dz = \int [\rho \vec{E} + \frac{1}{c} \vec{j} \times \vec{B}] dz$

$$\Rightarrow \vec{f} = \rho \vec{E} + \frac{1}{c} \vec{j} \times \vec{B} \quad \Leftarrow \quad \rho = \frac{1}{4\pi} \nabla \cdot \vec{E}$$

$$\vec{j} = \frac{\epsilon_0}{4\pi} (\nabla \times \vec{B}) - \frac{1}{4\pi c} \frac{\partial \vec{E}}{\partial t}$$

$$= \frac{1}{4\pi} (\nabla \cdot \vec{E}) \vec{E} + \frac{1}{4\pi} \left[(\nabla \times \vec{B}) \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \times \vec{B} \right]$$

$$-\frac{1}{c} \frac{\partial \vec{E}}{\partial t} \times \vec{B} = -\frac{1}{c} \frac{\partial}{\partial t} (\vec{E} \times \vec{B}) + \frac{1}{c} \vec{E} \times \frac{\partial \vec{B}}{\partial t} = -\frac{1}{c} \frac{\partial}{\partial t} (\vec{E} \times \vec{B}) - \vec{E} \times (\nabla \times \vec{E})$$

$$\Rightarrow \vec{f} = \frac{1}{4\pi} [(\nabla \cdot \vec{E}) \vec{E} - \vec{E} \times (\nabla \times \vec{E})] - \frac{1}{4\pi} (\vec{B} \times (\nabla \times \vec{B})) - \frac{1}{4\pi c} \frac{\partial}{\partial t} (\vec{E} \times \vec{B})$$

$$\nabla(E \cdot E) = 2(\vec{E} \cdot \nabla) \vec{E} + 2 \vec{E} \times (\nabla \times \vec{E}) \Rightarrow \vec{E} \times (\nabla \times \vec{E}) = \frac{\nabla E^2}{2} - (\vec{E} \cdot \nabla) \vec{E}$$

$$\Rightarrow \text{first term} = \frac{1}{4\pi} \left[(\nabla \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \nabla) \vec{E} - \frac{1}{2} \nabla E^2 \right]$$

$$-\vec{B} \times (\nabla \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{B} - \frac{1}{2} \nabla B^2 = [(\nabla \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \nabla) \vec{B} - \frac{1}{2} \nabla B^2]$$

$$\Rightarrow \vec{f} = \frac{1}{4\pi} [(\nabla \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \nabla) \vec{E} + (\vec{E} \cdot \vec{B}) \vec{B}] - \frac{1}{8\pi} \nabla(E^2 + B^2) - \frac{1}{c^2} \frac{\partial}{\partial t} \vec{S}$$

7B

Let's represent it in terms of $f_i = \nabla_j T_{ji} - \underbrace{\frac{1}{c^2}}_{\text{S}_i} \frac{\partial}{\partial t} S_i$

we define $T_{ij} = \frac{1}{4\pi} (E_i E_j - \frac{1}{2} \delta_{ij} E^2)$

$$+ \frac{1}{4\pi} (B_i B_j - \frac{1}{2} \delta_{ij} B^2)$$

check

$$\nabla_i T_{ij} = \frac{1}{4\pi} \left[(\nabla \cdot E) E_j - \frac{1}{2} \nabla_j E^2 \right] + (E \rightarrow B)$$

$$+ E_i \partial_i E_j$$

 \Rightarrow

$$F_i = \int (\nabla_j T_{ji} - \frac{1}{c^2} \frac{\partial}{\partial t} S_i) d^3 r$$

$$= \iint_s T_{ji} d\alpha_j - \frac{1}{c^2} \frac{\partial}{\partial t} \int S_i d^3 r$$

$$: \frac{d}{dt} \left[\int \frac{1}{c^2} S_i d^3 r \right] + \iint (-T_{ji}) d\alpha_j = -F_i \leftarrow$$

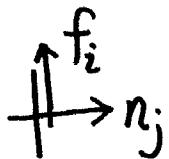
momentum density

 S_i : energy current $= c^2$ mass current

momentum flow

momentum
transform
to mechanical
degree of
freedom T_{ij} is force (per area) in the i -th direction↑ acting on an element of surface oriented in the j -th direction.

stress tensor.



$$\Rightarrow \frac{d}{dt} \int d^3 r \left(\frac{1}{c^2} S_i + f_i \right) = \iint \nabla_j T_{ji} d^3 r$$

$$\Rightarrow \boxed{\frac{\partial}{\partial t} \left[\underset{i}{P_{\text{mech}}} + \underset{i}{P_{\text{em}}} \right] = \nabla_j T_{ji}}$$