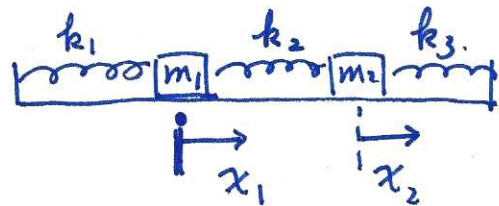


Lect 18: Oscillation (III), Coupled ~~mode~~ - normal modes

§1: Two oscillators coupled by three springs. Assume m_1 and m_2 have displacements x_1 and x_2 , respectively



$$F_1 = m_1 \ddot{x}_1 = -k_1 x_1 - k_2 (x_1 - x_2) = -(k_1 + k_2) x_1 + k_2 x_2$$

$$F_2 = m_2 \ddot{x}_2 = -k_3 x_2 + k_2 (x_2 - x_1) = k_2 x_1 - (k_2 + k_3) x_2$$

$$\Rightarrow \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} = - \begin{pmatrix} \frac{k_1 + k_2}{m_1} & \frac{-k_2}{m_1} \\ \frac{-k_2}{m_2} & \frac{k_2 + k_3}{m_2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

consider a special case $k_1 = k_2 = k_3 = k$ and $m_1 = m_2 = m$

$$\Rightarrow \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} = - \frac{k}{m} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\text{try } \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^{-i\omega t} \Rightarrow \omega^2 \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \frac{k}{m} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\text{define } \omega^2 = \frac{k}{m} \lambda \Rightarrow \det \begin{pmatrix} 2 - \lambda & -1 \\ -1 & 2 - \lambda \end{pmatrix} = 0$$

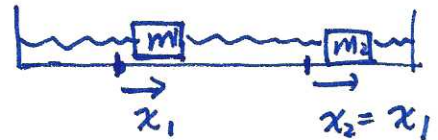
$$(\lambda - 2)^2 - 1 = \lambda^2 - 4\lambda + 3 = 0 \Rightarrow \lambda_1 = 1, \quad \lambda_2 = 3$$

(2)

For 1st mode, $\lambda_1 = 1 \Rightarrow \begin{bmatrix} 2-1 & -1 \\ -1 & 2-1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = 0$

$\Rightarrow a_1 = a_2$ or $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-i\omega_1 t}$

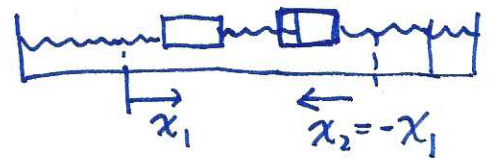
$\omega_1 = \sqrt{k/m}$



2nd mode $\lambda_2 = 3 \Rightarrow \begin{bmatrix} 2-3 & -1 \\ -1 & 2-3 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = 0$

$a_1 + a_2 = 0$ or $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-i\omega_2 t}$

$\omega_2 = \sqrt{3k/m}$



The general solution

$X(t) = A_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-i\omega_1 t} + A_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-i\omega_2 t}$

→ take real part

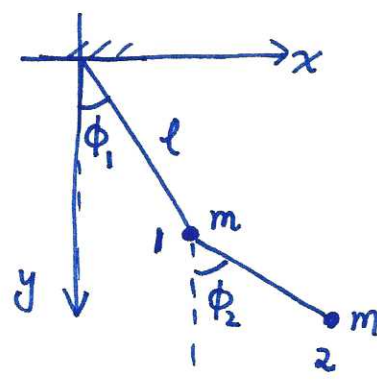
$X(t) = |A_1| \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos(\omega_1 t - \delta_1) + |A_2| \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos(\omega_2 t - \delta_2)$

* Normal coordinate $\xi_1 = \frac{1}{2}(x_1 + x_2)$, $\xi_2 = \frac{1}{2}(x_1 - x_2)$

$\Rightarrow \begin{pmatrix} \ddot{\xi}_1 \\ \ddot{\xi}_2 \end{pmatrix} = -\frac{k}{m} \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \leftarrow \begin{matrix} \xi_1, \xi_2 \text{ decoupled} \\ \text{or diagonal.} \end{matrix}$

§ Double pendulum

①



$$\textcircled{1} \quad x_1 = l \sin \phi_1 \quad y_1 = l \cos \phi_1$$

$$\Rightarrow v_1^2 = l^2 [\cos^2 \phi_1 \dot{\phi}_1^2 + \sin^2 \phi_1 \dot{\phi}_1^2] = l^2 \dot{\phi}_1^2$$

$$x_2 = l [\sin \phi_1 + \sin \phi_2] \quad y_2 = l [\cos \phi_1 + \cos \phi_2]$$

$$v_2^2 = [\dot{x}_2^2 + \dot{y}_2^2] = l^2 [(\cos \phi_1 \dot{\phi}_1 + \cos \phi_2 \dot{\phi}_2)^2 + (\sin \phi_1 \dot{\phi}_1 + \sin \phi_2 \dot{\phi}_2)^2]$$

$$= l^2 [\dot{\phi}_1^2 + \dot{\phi}_2^2 + 2 \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2)]$$

$$\Rightarrow T = \frac{1}{2} m l^2 \dot{\phi}_1^2 + \frac{1}{2} m l^2 [\dot{\phi}_1^2 + \dot{\phi}_2^2 + 2 \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2)]$$

$$= m l^2 \dot{\phi}_1^2 + \frac{1}{2} m l^2 \dot{\phi}_2^2 + m l^2 \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2)$$

$$u = - m g l \cos \phi_1 - m g l [\cos \phi_1 + \cos \phi_2]$$

$$\Rightarrow \mathcal{L} = T - u = m l^2 [\dot{\phi}_1^2 + \frac{1}{2} \dot{\phi}_2^2 + \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2)] + m g l [2 \cos \phi_1 + \cos \phi_2]$$

$$\textcircled{2} \quad \text{keep to 2nd order} \quad \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2) \simeq \dot{\phi}_1 \dot{\phi}_2 (1 - \frac{1}{2}(\phi_1 - \phi_2)^2) \simeq \dot{\phi}_1 \dot{\phi}_2$$

$$2 \cos \phi_1 + \cos \phi_2 \simeq -\phi_1^2 - \frac{1}{2} \phi_2^2 + \text{const}$$

$$\Rightarrow \mathcal{L} = m l^2 [\dot{\phi}_1^2 + \frac{1}{2} \dot{\phi}_2^2 + \dot{\phi}_1 \dot{\phi}_2] - m g l \phi_1^2 - \frac{1}{2} m g l \phi_2^2$$

$$\frac{\partial L}{\partial \phi_1} = -2mgl \phi_1 \quad \frac{\partial L}{\partial \dot{\phi}_1} = 2m\ell^2 \dot{\phi}_1 + m\ell^2 \dot{\phi}_2$$

$$\Rightarrow \frac{\partial L}{\partial \phi_1} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}_1} \right) \Rightarrow -2mgl \phi_1 = 2m\ell^2 \ddot{\phi}_1 + m\ell^2 \ddot{\phi}_2$$

or $2\ddot{\phi}_1 + \ddot{\phi}_2 = -\frac{2g}{\ell} \phi_1$

$$\frac{\partial L}{\partial \phi_2} = -mgl \phi_2 \quad \frac{\partial L}{\partial \dot{\phi}_2} = m\ell^2 \dot{\phi}_2 + m\ell^2 \dot{\phi}_1$$

$$\frac{\partial L}{\partial \phi_2} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}_2} \right) \Rightarrow -mgl \phi_2 = m\ell^2 \ddot{\phi}_2 + m\ell^2 \ddot{\phi}_1$$

\Rightarrow $\ddot{\phi}_1 + \ddot{\phi}_2 = -\frac{g}{\ell} \phi_2$

$$\Rightarrow \frac{d^2}{dt^2} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = -\frac{g}{\ell} \begin{pmatrix} 2 & -1 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix}$$

③ Plug in $\begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^{-i\omega t} \Rightarrow$

$$\omega^2 \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \frac{g}{\ell} \begin{pmatrix} 2 & -1 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \Rightarrow \frac{g}{\ell} \begin{pmatrix} 2-\lambda & -1 \\ -2 & 2-\lambda \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 0$$

where $\omega^2 = \frac{g}{\ell} \lambda$

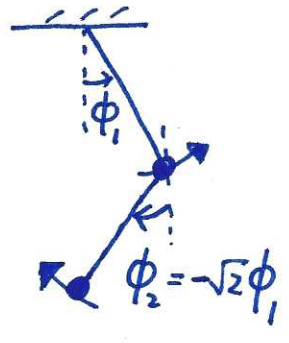
$$\Rightarrow \det \begin{bmatrix} 2-\lambda & -1 \\ -2 & 2-\lambda \end{bmatrix} = 0 \Rightarrow (\lambda-2)^2 + 2 = 0$$

$$\lambda^2 - 4\lambda + 2 = 0 \Rightarrow \lambda = 2 \pm \sqrt{2}$$

$$\Rightarrow \omega_1^2 = (2 + \sqrt{2}) g/L \qquad \omega_2^2 = (2 - \sqrt{2}) g/L$$

④ Normal modes

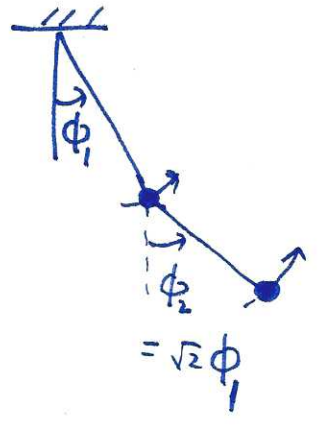
$$\text{For } \omega_1^2 = (2 + \sqrt{2}) g/L \Rightarrow \begin{bmatrix} 2 - (2 + \sqrt{2}) & -1 \\ -2 & 2 - (2 + \sqrt{2}) \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 0$$



$$\begin{bmatrix} -\sqrt{2} & -1 \\ -2 & -\sqrt{2} \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 0 \Rightarrow \sqrt{2} a_1 + a_2 = 0 \Rightarrow \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -\sqrt{2} \end{pmatrix} e^{-i\omega t}$$

$$\text{For } \omega_2^2 = (2 - \sqrt{2}) g/L \Rightarrow \begin{bmatrix} 2 - (2 - \sqrt{2}) & -1 \\ -2 & 2 - (2 - \sqrt{2}) \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} \sqrt{2} & -1 \\ -2 & \sqrt{2} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 0$$

$$\Rightarrow a_2 = \sqrt{2} a_1 \Rightarrow \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ \sqrt{2} \end{pmatrix} e^{-i\omega t}$$



§ The general case — quadratic Lagrangian (harmonic approx)

$$T = \frac{1}{2} \sum_{j,k} M_{jk} \dot{q}_j \dot{q}_k = \dots \quad q = (q_1, \dots, q_n)$$

$$U(q) = U(0) + \frac{1}{2} \sum_{j,k} K_{jk} q_j q_k \quad \leftarrow q=0 \text{ is the equilibrium position}$$

$$L = T - U(q)$$

$$\Rightarrow \frac{\partial L}{\partial q_i} = \sum_j K_{ij} q_j$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) = \frac{\partial L}{\partial q_i}$$

$$\frac{\partial L}{\partial \dot{q}_i} = \sum_j M_{ij} \dot{q}_j$$

$$\Rightarrow \sum_j K_{ij} q_j = \sum_j M_{ij} \ddot{q}_j$$

$$\Rightarrow M \ddot{q} = -K q$$

where M and K are $n \times n$ matrices, and they are symmetric

$$\text{Set } q = \begin{bmatrix} q_1 \\ \vdots \\ q_n \end{bmatrix} e^{-i\omega t}$$

$$\Rightarrow \left[K - \omega^2 M \right] \begin{bmatrix} q_1 \\ \vdots \\ q_n \end{bmatrix} = 0$$

or $\left[M^{-1} K - \omega^2 \right] \begin{bmatrix} q_1 \\ \vdots \\ q_n \end{bmatrix} = 0$, then ω^2 is an eigenvalue of the matrix $M^{-1} K$,

and $\begin{bmatrix} q_1 \\ \vdots \\ q_n \end{bmatrix}$ is an eigen-vector \leftarrow the normal modes!

For each eigen-frequency ω_i^2 , we have the eigenvector $\begin{bmatrix} q_1^{(i)} \\ \vdots \\ q_n^{(i)} \end{bmatrix}$

Then the general solution is

$$q(t) = \begin{bmatrix} q_1 \\ \vdots \\ q_n \end{bmatrix} = \sum_i A_i e^{-i\omega_i t}$$

$$= \sum_i A^{(i)} \begin{bmatrix} q_1^{(i)} \\ \vdots \\ q_n^{(i)} \end{bmatrix} e^{-i\omega_i t} \rightarrow \text{finally take real part.}$$